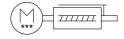
Mini slide unit EGSS-BS-KF-45-150-10P-ST-M-H1-PLK-AA

FESTO

Part number: 8083819





Data sheet

Size 45 Stroke reserve 0 0 mm Reversing backlash 150 µm Screw diameter 10 mm Spindle pitch 10 mm/U Type code EGSS Mounting position Any Guide Recirculating ball bearing guide Structural design Electrical mini-slide with ball screw drive With integrated drive Motor type Stepper motor Homing Fixed stop block, negative Reference switch Spindle type Ball screw drive Symbol 00997294 Position sensing Motor encoder For proximity sensor Rotor position sensor Absolute encoder, single-turn Rotor position sensor measuring principle Magnetic Additional functions User interface Integrated end-position sensing Display LED Ready status indication LED Max. acceleration 5 m/s² Repetition accuracy 40.015 mm Awx. speed 0.25 m/s Repetition accuracy 40.015 mm Awx. current of digital logic outputs 0000 mA Max. current of digital logic outputs 100 mA Max. current of digital logic outputs 24 V	Feature	Value
Stroke reserve 0 mm Reversing backlash 150 μm Screw diameter 10 mm Type code EGS5 Mounting position Any Guide Recirculating ball bearing guide Structural design Electrical mini-slide with ball screw drive With integrated drive With integrated drive With integrated drive Motor type Stepper motor Homing Fixed stop block, negative Reference switch Spindle type Ball screw drive Roper motor Symbol 00997294 Position sensing Motor encoder For proximity sensor Rotor position sensor measuring principle Magnetic Additional functions User interface integrated end-position sensing Display ED Ready status indication ED Max. acceleration 5 m/s² Repetition accuracy 100% Resulting and 100% Russ, current of digital logic outputs 100 mA Max. current of digital logic outputs	Working stroke	150 mm
Reversing backlash Screw diameter 10 mm Spindle pitch 10 mm/U Type code EGSS Mounting position Any Guide Recirculating ball bearing guide Structural design Electrical mini-slide with ball screw drive With integrated drive Motor type Stepper motor Homing Fixed stop block, negative Reference switch Spindle type Ball screw drive Symbol O0997294 Position sensing Motor encoder For proximity sensor Rotor position sensor measuring principle Additional functions Display LED Ready status indication LED Max. acceleration S m/s² Max. speed Q.25 m/s Repetition accuracy Characteristics of digital logic outputs Nax. current of digital logic outputs Max. current of digital logic outputs DC nominal voltage	Size	45
Screw diameter 10 mm Spindle pitch 10 mm/U Type code EGSS Mounting position	Stroke reserve	0 mm
Spindle pitch 10 mm/U Type code EGSS Mounting position Any Guide Recirculating ball bearing guide Structural design Electrical mini-slide with ball screw drive With integrated drive Motor type Stepper motor Homing Fixed stop block, negative Reference switch Spindle type Ball screw drive Symbol 00997294 Position sensing Motor encoder For proximity sensor Rotor position sensor measuring principle Magnetic Additional functions User interface Integrated end-position sensing Display LED Ready status indication LED Max. acceleration 5 m/s² Max. acceleration accuracy 2.015 mm Characteristics of digital logic outputs Configurable Not galvanically isolated Duty cycle 100% Insulation protection class B Max. current of digital logic outputs 100 mA Max. current of of digital logic outputs 24 V	Reversing backlash	150 µm
Type code Mounting position Any Guide Recirculating ball bearing guide Structural design Electrical mini-slide with ball screw drive With integrated drive Motor type Stepper motor Fixed stop block positive Fixed stop block, negative Reference switch Spindle type Ball screw drive Symbol 00997294 Position sensing Motor encoder For proximity sensor Rotor position sensor Absolute encoder, single-turn Rotor position sensor measuring principle Additional functions User interface Integrated end-position sensing Display LED Ready status indication LED Max. acceleration Max. acceleration S m/s² Rotor position sensing Configurable Not galvanically isolated Not galvanically isolated Duty cycle 100% Insulation protection class B Max. current of digital logic outputs Max. current on sumption Max. current on sumption Jey Not Max. Succeleration Any Recirculating ball bearing guide Electrical mini-slide with ball screw drive With integrated drive With integrated on spile with ball screw drive With integrated end-position Recirculation LED Assistance of the provided of the pro	Screw diameter	10 mm
Mounting position Any Guide Recirculating ball bearing guide Structural design Electrical mini-slide with ball screw drive With integrated drive Motor type Stepper motor Homing Fixed stop block, negative Reference switch Spindle type Ball screw drive Symbol 00997294 Position sensing Motor encoder For proximity sensor Rotor position sensor measuring principle Magnetic Additional functions User interface Integrated end-position sensing Display LED Ready status indication LED Max. acceleration 5 m/s² Max. speed 0.25 m/s Repetition accuracy ±0.015 mm Characteristics of digital logic outputs Configurable Not galvanically isolated Duty cycle 100% Insulation protection class B Max. current of digital logic outputs 100 mA Max. current consumption 3000 mA DC nominal voltage 24 V	Spindle pitch	10 mm/U
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With ball screw drive With integrated drive Motor type Stepper motor Homing Fixed stop block positive Fixed stop block, negative Reference switch Spindle type Ball screw drive Symbol 00997294 Position sensing Motor encoder For proximity sensor Rotor position sensor Absolute encoder, single-turn Rotor position sensor measuring principle Magnetic Additional functions User interface Integrated end-position sensing Display LED Ready status indication LED Max. acceleration 5 m/s² Max. speed 0.25 m/s Repetition accuracy 40.015 mm Characteristics of digital logic outputs Configurable Not galvanically isolated Duty cycle 100% Insulation protection class B Max. current of digital logic outputs 100 mA Max. current consumption 3000 mA DC nominal voltage 24 V	Guide	Recirculating ball bearing guide
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Fixed stop block, negative Reference switch Spindle type Symbol O0997294 Position sensing Motor encoder For proximity sensor Rotor position sensor measuring principle Additional functions User interface Integrated end-position sensing Display LED Ready status indication LED Max. acceleration S m/s² Max. speed Acceleration accuracy Characteristics of digital logic outputs Duty cycle Insulation protection class B Max. current of digital logic outputs Max. current consumption DC nominal voltage Ell Size Advive Ball screw drive Advive Absolute encoder, single-turn Magnetic Magnetic User interface Integrated end-position sensing User interface Integrated end-position sensing Configuration sensor Ell Configurable Not galvanically isolated Duty cycle 100% Insulation protection class B Max. current of digital logic outputs According and	Motor type	Stepper motor
Symbol 00997294 Position sensing Motor encoder For proximity sensor Rotor position sensor Absolute encoder, single-turn Rotor position sensor measuring principle Magnetic Additional functions User interface Integrated end-position sensing Display LED Ready status indication LED Max. acceleration 5 m/s² Max. speed 0.25 m/s Repetition accuracy ±0.015 mm Characteristics of digital logic outputs Configurable Not galvanically isolated Duty cycle 100% Insulation protection class B Max. current of digital logic outputs 100 mA Max. current consumption 3000 mA DC nominal voltage 24 V	Homing	Fixed stop block, negative
Position sensing Motor encoder For proximity sensor Rotor position sensor Rotor position sensor measuring principle Additional functions User interface Integrated end-position sensing Display LED Ready status indication LED Max. acceleration Max. speed O.25 m/s Repetition accuracy Characteristics of digital logic outputs Duty cycle Insulation protection class B Max. current of digital logic outputs DC nominal voltage Motor encoder For proximity sensor Absolute encoder, single-turn Magnetic LED Magnetic User interface Integrated end-position sensing Duser integrated end-position sensing User integrated end-position sensing Dusprinciple Magnetic User interface Integrated end-position sensing Dusprinciple Magnetic Adsolute encoder, single-turn Magnetic Dusprinciple Magnetic User interface Integrated end-position sensing User interface Integrated end-position sensing User interface Integrated end-position sensing Display LED Configurable Not galvanically isolated Not galvanically isolated Down Max. current of digital logic outputs Dom Ma Max. current consumption Dom Ma Max. current consumption Dom Ma D	Spindle type	Ball screw drive
For proximity sensor Rotor position sensor measuring principle Magnetic Additional functions User interface Integrated end-position sensing Display LED Ready status indication LED Max. acceleration 5 m/s² Max. speed 0.25 m/s Repetition accuracy ±0.015 mm Characteristics of digital logic outputs Not galvanically isolated Duty cycle 100 % Insulation protection class B Max. current of digital logic outputs 100 mA Max. current consumption 3000 mA DC nominal voltage 24 V	Symbol	00997294
Rotor position sensor measuring principle Additional functions User interface Integrated end-position sensing Display LED Ready status indication LED Max. acceleration 5 m/s² Max. speed 0.25 m/s Repetition accuracy ±0.015 mm Characteristics of digital logic outputs Characteristics of digital logic outputs Duty cycle Insulation protection class Max. current of digital logic outputs Magnetic User interface Integrated end-position sensing LED Configuration Configuration Not galvanically isolated B Max. current of digital logic outputs 100 mA Max. current consumption 3000 mA DC nominal voltage 24 V	Position sensing	
Additional functions User interface Integrated end-position sensing Display LED Ready status indication LED Max. acceleration 5 m/s² Max. speed 0.25 m/s Repetition accuracy ±0.015 mm Characteristics of digital logic outputs Configurable Not galvanically isolated Duty cycle Insulation protection class B Max. current of digital logic outputs DO mA Max. current consumption DC nominal voltage 24 V	Rotor position sensor	Absolute encoder, single-turn
DisplayLEDReady status indicationLEDMax. acceleration5 m/s²Max. speed0.25 m/sRepetition accuracy±0.015 mmCharacteristics of digital logic outputsConfigurable Not galvanically isolatedDuty cycle100%Insulation protection classBMax. current of digital logic outputs100 mAMax. current consumption3000 mADC nominal voltage24 V	Rotor position sensor measuring principle	Magnetic
Ready status indication Max. acceleration S m/s² Max. speed 0.25 m/s Repetition accuracy ±0.015 mm Characteristics of digital logic outputs Configurable Not galvanically isolated Duty cycle 100% Insulation protection class B Max. current of digital logic outputs Max. current consumption DC nominal voltage 24 V	Additional functions	
Max. acceleration 5 m/s² Max. speed 0.25 m/s Repetition accuracy ±0.015 mm Characteristics of digital logic outputs Configurable Not galvanically isolated Duty cycle 100% Insulation protection class B Max. current of digital logic outputs 100 mA Max. current consumption 3000 mA DC nominal voltage 24 V	Display	LED
Max. speed 0.25 m/s Repetition accuracy ±0.015 mm Characteristics of digital logic outputs Configurable Not galvanically isolated Duty cycle 100% Insulation protection class B Max. current of digital logic outputs 100 mA Max. current consumption 3000 mA DC nominal voltage 24 V	Ready status indication	LED
Repetition accuracy ±0.015 mm Characteristics of digital logic outputs Configurable Not galvanically isolated Duty cycle 100% Insulation protection class B Max. current of digital logic outputs 100 mA Max. current consumption 3000 mA DC nominal voltage 24 V	Max. acceleration	5 m/s ²
Characteristics of digital logic outputs Configurable Not galvanically isolated Duty cycle 100% Insulation protection class Max. current of digital logic outputs Max. current consumption DC nominal voltage Configurable Not galvanically isolated 100 M 3000 mA	Max. speed	0.25 m/s
Not galvanically isolated Duty cycle 100% Insulation protection class B Max. current of digital logic outputs 100 mA Max. current consumption 3000 mA DC nominal voltage 24 V	Repetition accuracy	±0.015 mm
Insulation protection class Max. current of digital logic outputs Max. current consumption DC nominal voltage B 100 mA 3000 mA 24 V	Characteristics of digital logic outputs	
Max. current of digital logic outputs 100 mA Max. current consumption 3000 mA DC nominal voltage 24 V	Duty cycle	100%
Max. current consumption 3000 mA DC nominal voltage 24 V	Insulation protection class	В
DC nominal voltage 24 V	Max. current of digital logic outputs	100 mA
	Max. current consumption	3000 mA
Nominal current 3 A	DC nominal voltage	24 V
	Nominal current	3 A

Feature	Value
Parameterization interface	IO-Link®
	User interface
Rotor position sensor resolution	16 bit
Permissible voltage fluctuations	+/- 15 %
Power supply, type of connection	Plug
Power supply, connection technology	M12x1, T-coded as per EN 61076-2-111
Power supply, number of pins/wires	4
Power supply, connection pattern	00995989
Certification	RCM compliance mark
KC characters	KC EMC
CE marking (see declaration of conformity)	As per EU EMC directive As per EU RoHS directive
Vibration resistance	Transport application test with severity level 1 as per FN 942017-4 and EN 60068-2-6
Shock resistance	Shock test with severity level 1 as per FN 942017-5 and EN 60068-2-27
Corrosion resistance class (CRC)	0 - No corrosion stress
Storage temperature	-20 °C 60 °C
Relative air humidity	0 - 90 %
Degree of protection	IP40
Protection class	
Ambient temperature	0 °C 50 °C
Note on ambient temperature	Above an ambient temperature of 30°C, the power must be reduced by
	2% per K.
Fixed bearing dynamic basic load rating	7413 N
Linear guide dynamic basic load rating	3240 N
Dynamic basic load rating, ball screw drive	3200 N
Max. force Fy	1314 N
Max. force Fz	1314 N
Max. torque Mx	8.14 Nm
Max. torque My	7.05 Nm
Max. torque Mz	7.05 Nm
Max. radial force on actuator shaft	340 N
Max. feed force Fx	120 N
Guide value for payload, horizontal	6 kg
Guide value for payload, vertical	6 kg
Ball screw drive statistical basic load rating	5900 N
Linear guide statistical basic load rating	5630 N
Feed constant	10 mm/U
Statistical fixed bearing load rating	3966 N
Reference value, running performance	5000 km
Maintenance interval	Life-time lubrication
Moving mass at 0 mm stroke	212 g
Additional weight per 10 mm stroke	63 g
Basic weight with 0 mm stroke	1238 g
Product weight	2181 g
Additional moving mass per 10 mm stroke	30 g
Number of digital logic outputs 24 V DC	2
Number of digital logic inputs	2 2
Logic input specification	Based on IEC 61131-2, type 1
Work range of logic input	24 V
IO-Link®, SIO mode support	Yes
Characteristics of logic input	Configurable
	Not galvanically isolated
IO-Link®, protocol version	Device V 1.1

Feature	Value
IO-Link®, communication mode	COM3 (230.4 kBd)
IO-Link®, port class	A
IO-Link®, number of ports	1
IO-Link®, process data width OUT	2 Byte
IO-Link®, process data content OUT	1 bit (move in) 1 bit (move out) 1 bit (quit error)
IO-Link®, process data width IN	2 Byte
IO-Link®, process data content IN	1 bit (state device) 1 bit (state move) 1 bit (state in) 1 bit (state out)
IO-Link®, service data contents IN	32 bit force 32 bit position 32 bit speed
IO-Link®, minimum cycle time	1 ms
IO-Link®, data memory required	500 byte
Max. cable length	15 m outputs 15 m inputs 20 m for IO-Link® operation
Switching logic at outputs	PNP (positive switching)
Input switching logic	PNP (positive switching)
IO-Link®, Connection technology	Plug
Logic interface, connection type	Plug
Logic interface, connection technology	M12x1, A-coded as per EN 61076-2-101
Logic interface, number of poles/wires	8
Logic interface, connection pattern	00992264
Type of mounting	With internal thread With centering sleeve With accessories With cylindrical pin
Note on materials	Contains paint-wetting impairment substances RoHS-compliant
Slide carriage material	Roller bearing steel
Guide rail material	Roller bearing steel
Housing material	Wrought aluminum alloy, anodized
Material of yoke plate	Wrought aluminum alloy, anodized
Piston rod material	High-alloy stainless steel
Slide material	Wrought aluminum alloy, anodized
Spindle nut material	Roller bearing steel
Spindle material	Roller bearing steel